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Generated Pin Manager File

Company:

Microchip Technology Inc.

File Name:

pin\_manager.c

Summary:

This is the Pin Manager file generated using PIC10 / PIC12 / PIC16 / PIC18 MCUs

Description:

This header file provides implementations for pin APIs for all pins selected in the GUI.

Generation Information :

Product Revision : PIC10 / PIC12 / PIC16 / PIC18 MCUs - 1.81.8

Device : PIC16F1619

Driver Version : 2.11

The generated drivers are tested against the following:

Compiler : XC8 2.36 and above

MPLAB : MPLAB X 6.00

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```

#include "pin_manager.h"

#include <xc.h>

#include "mcc.h"

#define Rx_out PORTAbits.RA2

void (*IOCCF3_InterruptHandler)(void);

void PIN_MANAGER_Initialize(void)
{
    /**
    LATx registers
    */
    LATA = 0x00;
    LATB = 0x00;
    LATC = 0x00;

    /**
    TRISx registers
    */
    TRISA = 0x31;
    TRISB = 0x30;
    TRISC = 0x2D;

    /**
    ANSELx registers
    */
    ANSELC = 0x05;
    ANSELB = 0x30;
    ANSELA = 0x11;

    /**
    WPUx registers
    */
    WPUB = 0x00;
    WPUA = 0x00;
    WPUC = 0x00;
    OPTION_REGbits.nWPUEN = 1;

    /**
    ODX registers
    */
    ODCONA = 0x00;
    ODCONB = 0x00;
    ODCONC = 0x00;

    /**
    SLRCONx registers
    */
    SLRCONA = 0x37;
    SLRCONB = 0xF0;

```

```

SLRCONC = 0xFF;

/**
INLVLx registers
*/
INLVLA = 0x3F;
INLVLB = 0xF0;
INLVLC = 0xFF;

/**
IOCx registers
*/
//interrupt on change for group IOCCF - flag
IOCCFbits.IOCCF3 = 0;
//interrupt on change for group IOCCN - negative
IOCCNbits.IOCCN3 = 1;
//interrupt on change for group IOCCP - positive
IOCCPbits.IOCCP3 = 0;

// register default IOC callback functions at runtime; use these methods to
register a custom function
IOCCF3_SetInterruptHandler(IOCCF3_DefaultInterruptHandler);

// Enable IOCI interrupt
INTCONbits.IOIE = 1;
}

void PIN_MANAGER_IOC(void)
{
    // interrupt on change for pin IOCCF3
    if(IOCCFbits.IOCCF3 == 1)
    {
        IOCCF3_ISR();
    }
}

/**
IOCCF3 Interrupt Service Routine
*/
void IOCCF3_ISR(void) {

    // Add custom IOCCF3 code

    // The DTR/RTS signal has just gone low, so switch to Rx immediately

        // switch transceiver to Rx mode
        Rx_out = 1;
        __delay_ms(50);
        Rx_out = 0;
}

```

```

    // Call the interrupt handler for the callback registered at runtime
    if(IOCCF3_InterruptHandler)
    {
        IOCCF3_InterruptHandler();
    }
    IOCCFbits.IOCCF3 = 0;
}

/**
 * Allows selecting an interrupt handler for IOCCF3 at application runtime
 */
void IOCCF3_SetInterruptHandler(void (* InterruptHandler)(void)){
    IOCCF3_InterruptHandler = InterruptHandler;
}

/**
 * Default interrupt handler for IOCCF3
 */
void IOCCF3_DefaultInterruptHandler(void){
    // add your IOCCF3 interrupt custom code
    // or set custom function using IOCCF3_SetInterruptHandler()
}

/**
 * End of File
 */

```